

# DIPAM PATEL

Hyattsville, MD, USA • +1 (240) 714-8606 • [dipu18@terpmail.umd.edu](mailto:dipu18@terpmail.umd.edu) • [ter.ps/dipam](http://ter.ps/dipam)

**Interests:** Machine Learning, ROS, Computer Vision, Augmented Reality

## EDUCATION

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### Master of Engineering in Robotics

**Expected: December 2019**

University of Maryland, College Park, MD, USA

**Current GPA: 3.77**

**Relevant Courses:** *Perception and Planning for Autonomous Robots, Computer Vision, Control of Robotic Systems, Robot Learning, AI & Deep Learning Frameworks, 4-Course Self-Driving Cars Specialization*

### Bachelor of Engineering in Mechanical

**June 2016**

Gujarat Technological University, Ahmedabad, India

**Cumulative GPA: 3.42**

## EXPERIENCE

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### Summer Internship

**June 2019 - Present**

Internship Trainee at Airgility Inc., College Park

- Involved with Deep Learning focused on Object Detection using Tensorflow API for Autonomous Takeoff & Landing of Drones
- Developing Semantic Segmentation based algorithm for Detection of Humans and Objects of Interest

### Publications

- Heuristic Based Optimal Path Planning for Neurosurgical Tumor Ablation, *SPIE Medical Imaging Conference, San Diego, California* **February 2019**  
Reduced the time spent in manual planning and provided an optimum path for the biopsy needle to penetrate through the skull right to the axis of the tumor while avoiding critical structures and maximizing safe ablation region
- Six Sigma Improvement Opportunities in Working Techniques of Bachhpan NGO, *International Conference on Emerging Trends in Mechanical Engineering (ICETME), Vallabh Vidyanagar* **February 2017**  
Improved the teaching-learning process and the overall performance of the slum students & volunteers
- Mechanically Operated Cart for Pesticide Sprayer for Agriculture, *International Journal of Innovative Research in Science, Engineering & Technology (IJIRSET), Volume-5, Issue-5* **May 2016**  
Eliminated the efforts for pumping the pesticides manually and mechanically automatized the entire process

### Community Service

**October 2012 – May 2016**

Volunteer, Documentation Head & Chief Operating Officer (COO) at *Bachhpan Charitable Foundation for Children Welfare (a student-run organization which works against child-labor)*

## PROJECTS

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- Deep Q-Network based Lane Following Toy Car  
Training a Toy Robot Car using Deep Q-Network to drive in its Lane
- Emergency Vehicle Detection using Tensorflow Deep Learning API (Winner of Northrop Grumman Competition)  
Recognized and located vehicles from images/videos using the concepts of transfer learning and faster RCNN
- Lane Detection to mimic lane departure warning systems used in Self-driving cars  
Used the concepts of hough lines, region of interest and vanishing point, lanes were detected for real-world scenarios
- Traffic sign recognition involving Detection and Classification  
Taught a model in MATLAB to recognize traffic signs and tested it for the real-world scenarios
- Face and Eye Detection using Haar Cascade Classifiers in OpenCV  
Using the cascade function trained from positive and negative images to identify features of the human face
- Location based Augmented Reality Scavenger Hunt game (*Ongoing*)  
Developing an interactive AR game using the GPS+AR package in Unity
- Forward & Inverse Kinematics of the Aldebaran NAO robot- Computation, validation & simulation  
Verified the forward & inverse kinematics of NAO robot and simulated their movements in Choregraphe & Webots

## TECHNICAL SKILLS

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**Programming Languages/Tools/OS:** Python, C++, OpenCV, MATLAB, V-REP, Unity, ROS, Gazebo

**Machine Learning Tools/Modules:** Tensorflow, Scikit-learn, Regression, Clustering, Cross-validation

**Hardware:** Raspberry Pi, Arduino, Leap Motion, Basic Electronics Repairing